

## TF-Luna LiDAR (Underwater)

TF-Luna is a single-point LiDAR, based on ToF principle. Mainly used for stable, accuracy and high-frame rate range detection. The product is built with algorithms adapted to various application environments and adopts multiple adjustable configurations and parameters, especially suitable for applications on outdoor swimming pool cleaning robots under strong sunlight.

## Main Product Features

- Small size
- High precision
- Low power
- consumption
- Low cost

## Main Application Scenarios

- Pool mapping
- Obstacle avoidance underwater
- Step detection
- Waterline detection



## **SPECIFICATIONS**

Description		Parameter Value	
Product performance	Operating range	5cm~55cm <sup>1</sup>	
	Accuracy	<3 cm <sup>1</sup>	
	Distance resolution	1cm	
	Frame rate	1-250Hz <sup>2</sup>	
	Ambient light immunity	70Klux	
	Operation temperature	-10°C~60°C	
	Enclose rating	/	
Optical parameters	Light source	VCSEL	
	Central wavelength	850nm	
	Photobiological safety	Class1 (IEC60825)	
	FOV	2°3	
Electrical parameters	Supply voltage	3.7V-5.2V	
	Average current	≤70mA	
	Power consumption	≤0.35W	
	Peak current	150mA	
	Communication level	LVTTL(3.3V)	
	Communication interface	UART, I²C, I/O	



Others	Dimension		35mm*21.25mm*12.5mm (L*W*H)	
	Housing		ABS+PC	
	Storage temperature		-20°C~75°C	
	Weight		<5g	
Communicati on Interface	UART		I <sup>2</sup> C	
	Default baud rate	115200(adjust able)	Max transmission rate	400kbps
	Data bit	8	Master/Slave mode	Slave
	Stop bit	1	Default address	0x10
	Parity	None	Address range	0x08~0x77
Dimensions	\$ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~		<u></u>	

1. The measurement distance is test with outdoors underwater, with the target object being common swimming pool wall tiles, under 25  $^\circ\!C$  conditions,

2. The Highest frame rate is 250Hz, the default frame rate is 100Hz. The customized update rate should be calculated by the formula: 500/n (n is more than 2).

3. This is a theoretical reference value.